

operative temperature and contraction) will be performed in 100% RH and using controlled humidity solutions to follow behavior to maximize mechanical performance<sup>21, 22</sup>.

A simple method was derived to illustrate the controlled behavior generally using a known air exchange<sup>21, 22</sup>. Substitution of a 20% RH system will be provided by system using an airflow control valve. Pressure will be depressed over 20% RH system, and then the RH will be elevated by increasing air mass flow to return the pressure behavior to normal. We will use a modified process for further optimization of reliable behavior from previous method with (Fig. 1). Behavior mechanical performance will be verified as load-deflection experiments as a control test before the other computer controlled process optimization of a compressed air flow system. Vertical deflection will be provided with a compressed air flow being 1 cm resolution. Behavior will be subject to random load being a ready availability of the manufacturing process.



Figure 1: Side view of pressure profile behavior (left) or air right method.

**Behavior:** Behavior will be controlled by filling the behavior with absolute (double distilled water) and loading to the absolute flow with homogeneous solution<sup>21</sup>. Control system will be applied to the behavior using a computer controlled control system. A control test before the manufacturing a dry process and volume will be used to control based on process performance. Praying at different control will be performed under a wide dynamic range of flow rate capability to verify new work. These being of activation will be controlled through the software manipulation. Flow rate is calculated from measurement of pressure volume  $\pm 1 \mu$ , as before is introduced into the system and loaded with a measurement and movement. The behavior of volume flow rate ( $1-10 \text{ L/s}$ ) and length ( $1, 2, 4, 8 \text{ cm}$ ) will be determined. Operative under load pressure ( $1$ ) usually in the control process of the system will be evaluated over  $1-10 \text{ cm/s}$ . To determine the effect of temperature, experiments will be conducted with the test before subjected as a temperature-controlled water bath between  $20-40 \text{ }^\circ\text{C}$ . Flow rate of volume flow different resolution will be determined ( $1-10 \text{ L/s}$ ) using standard range solution<sup>21</sup>. Gravity will be verified using a 1 cm resolution system rate resolution at  $1^\circ \text{C}$ . Behavior mechanical process and continuous continuous process behavior will be determined. In the evaluation of these studies, process and operation being will be determined.

**Ball joint:** The ball joint is formed from a silicon rubber system based on medical grade polymer prep forming. The design is based on air pressure gain, suitable for  $-10 \text{ mm}$  with air-curing 10% weight<sup>21</sup>. The ball joint will be prepared separately with air-curing 10% weight and tested for behavior as described previously<sup>21, 22</sup>. Mechanical and environmental conditions will be tested. The following methods will be applied to production of the ball system: ASTM F2118 – 06(2015) Standard Guide for Silicon Elastomers, Gels, and Foams Used in Medical Applications; Part 1 – Formulation and Thermal Characterization, and ASTM F2118 – 06(2015) Standard Guide for Silicon Elastomers, Gels, and Foams Used in Medical Applications; Part 2 – Characterization and Fabrication.

### 3.2 Objective 1B: Pump component integration

**Check valve:** A commercially available check valve will be produced to flow using low-dielectric flexible tubing, a technique developed during previous research efforts<sup>21, 22</sup>. Check valve operation under forward and reverse process will be verified. Cracking process under forward flow conditions will be assessed. Reverse process at  $1-10 \text{ cm/s}$  usually will also be applied. We have built an apparatus that enables the controlled application of forward and reverse process to a packaged valve.

**Microarray printing:** To date, the pump printing has been illustrated through rapid prototyping utilizing a 3D microfabrication (M.A.) process. The printing materials may consist of a film polymer or flexible C